

Learning and the Great Moderation

James Bullard Aarti Singh

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- Stability theorems: where are they?
- It's all rational expectations with limited information.

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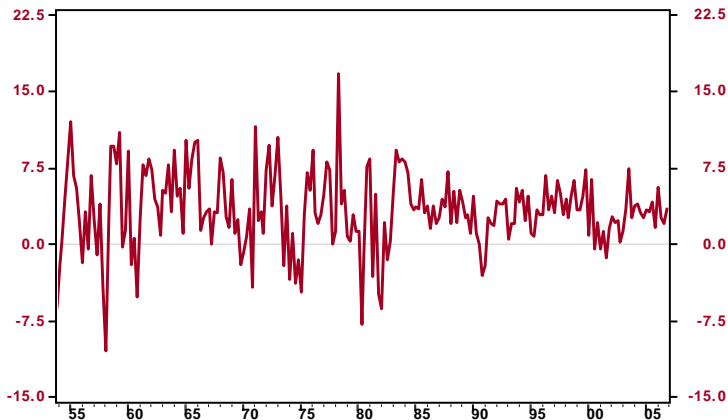
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- Perhaps the leading explanation: It was good luck, smaller and less frequent shocks to the economy.
- But why should shocks suddenly be fifty percent less volatile?

Real Gross Domestic Product

% Change - Annual Rate

SAAR, Bil.Chn.2000\$



Source: Bureau of Economic Analysis /Haver Analytics

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- ... but equilibrium behavior of private sector agents also changes in response to the smaller shocks.
- This is due to a *learning effect* which is the focus of the paper.
- So the moderation is due partly to good luck and partly to moderated private sector behavior.

How the shocks changed

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- Kim and Nelson (1999): Regimes moved closer, conditional variance unchanged.
- All of our economies will have this feature.

Learning effect

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- When regimes move closer with conditional variance constant, this inference problem becomes more difficult.
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- Macroeconomic variables are less volatile.

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- We include regime switching, incomplete information, and Bayesian learning.
- We solve the nonlinear model using perturbation methods.
- We isolate the learning effect we are interested in by comparing to well-known benchmarks without learning.

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- We compare two incomplete information economies with a variance reduction in output like that observed in the U.S. after 1984.
- In this comparison, we decompose the moderation:
 - the learning effect accounts for about 30 percent
 - less volatile shocks—“good luck”—accounts for about 70 percent.

Related literature

- Empirical: Kim and Nelson (1999, *REStat*) and McConnell and Perez-Quiros (2000, *AER*), Kim, Nelson, and Piger (2004, *JBES*), Stock and Watson (2003, *NBER Macro Annual*).

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- Good luck: Arias, Hansen, Ohanian (2006, *WP UCLA*), Ahmed, Levin, Wilson (2004, *REStat*).

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- Good luck: Arias, Hansen, Ohanian (2006, *WP UCLA*), Ahmed, Levin, Wilson (2004, *REStat*).
- Bayesian learning in general equilibrium: Van Nieuwerburgh and Veldkamp (2006, *JME*) concerning business cycle asymmetries, in asset pricing see Cagetti, Hansen, Sargent, Williams (2002, *Rev. Fin. Studies*), uncertain growth.

Standard equilibrium business cycle model

- Representative household with preferences
 $E_0 \sum_{t=0}^{\infty} \beta^t u(c_t, 1 - \ell_t)$, period utility

$$u(c_t, \ell_t) = \frac{[c_t^\theta (1 - \ell_t)^{1-\theta}]^{1-\tau}}{1 - \tau}. \quad (1)$$

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$$y_t = e^{z_t} f(k_t, \ell_t) = e^{z_t} k_t^\alpha \ell_t^{1-\alpha}, \quad (2)$$

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- Budget constraint, law of motion for capital standard.

Stochastic environment

- We assume z_t depends on a latent, unobserved state s_t through

$$z_t = (a_H + a_L)(s_t + \Delta\eta_t) - a_L, \quad (3)$$

where

$$z_t = \begin{cases} a_H + (a_H + a_L) \Delta \eta_t & \text{if } s_t = 1 \\ -a_L + (a_H + a_L) \Delta \eta_t & \text{if } s_t = 0 \end{cases}, \quad (4)$$

and $a_H \geq 0, a_L \geq 0, \eta_t \sim i.i.d. N(0, 1)$, and $\Delta > 0$ is a weighting parameter.

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- We assume s_t follows a first order Markov process.

The perturbation parameter

- The state s_t can be written as

$$s_t = \lambda_0 + \lambda_1 s_{t-1} + v_t, \quad (5)$$

and $\lambda_0 = (1 - q)$, $\lambda_1 = (p + q - 1)$, v_t white noise.

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- The stochastic process for technology can be written as

$$z_t = \zeta_0 + \zeta_1 z_{t-1} + \sigma \epsilon_t, \quad (6)$$

where $\zeta_0 = (a_H + a_L) \lambda_0 + \lambda_1 a_L - a_L$, $\zeta_1 = \lambda_1$,
 $\sigma = (a_H + a_L)$, and

$$\epsilon_t = v_t + \Delta \eta_t - \lambda_1 \Delta \eta_{t-1}. \quad (7)$$

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$$\epsilon_t = v_t + \Delta \eta_t - \lambda_1 \Delta \eta_{t-1}. \quad (7)$$

- $\sigma = a_H + a_L$ plays the role of the perturbation parameter in Auroba, Fernandez-Villaverde, and Rubio-Ramirez (2006) "AFR."

Information

- Unobserved: s_t , z_t , η_t , and v_t .

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- Beliefs are updated using Bayes' rule.

Social planner's problem

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- The second state is the state of expectations concerning the level of technology, so that

$$V(k_t, z_t^e) = \max_{c_t, \ell_t} u(c_t, 1 - \ell_t) + \beta E[V(k_{t+1}, z_{t+1}^e) | F_t] \quad (8)$$

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- We use second-order perturbation methods using a version of the code provided by Auroba et al (2006).

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to be standard, meaning $\tilde{\zeta}_0 = 0, \tilde{\zeta}_1 = 0.95, \sigma = 0.007,$ and $\sigma_\epsilon^2 = 1$ as in AFR (2005).

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- Since $\zeta_1 = p + q - 1$, we set $p = q = 0.975$. Then $\zeta_0 = 0$.

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- Since $\zeta_1 = p + q - 1,$ we set $p = q = 0.975$. Then $\zeta_0 = 0$.
- To get $\sigma_\epsilon = 1,$ we set $\Delta = 0.719$. This implies $\sigma\Delta = 0.005$.

TABLE 1.
Benchmark comparison.

Variable	AFR	Model
Output	1.2418	1.2398
Consumption	0.4335	0.4323
Hours	0.5714	0.5706
Investment	3.6005	3.5953
Capital	0.2490	0.2466

Table: A comparison of standard deviations of key endogenous variables for a standard equilibrium business cycle model (AFR) and the complete information version of the present model with regime switching. The addition of regime switching does not change the standard deviations appreciably.

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- In particular, we would like both conditional and unconditional standard deviations to remain unchanged.
- We only have one parameter, Δ , to use to keep both constant.
- But we can get close even when regime distance increases by a factor of three.

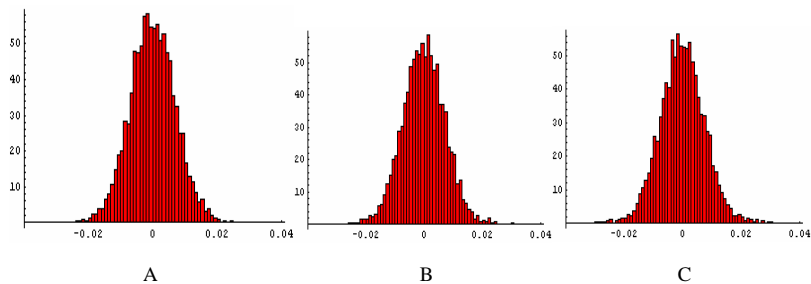


Figure: Shock distributions for economies *A*, *B*, and *C* are very similar, but the regimes for economy *B* are twice as far apart as those for economy *A*. For economy *C*, the regimes are three times as far apart. Figures are drawn for 6,500 draws from each distribution.

TABLE 2. INCREASING σ
Economy

	A	B	C
Parameter values			
a_H	0.0035	0.0070	0.0105
a_L	0.0035	0.0070	0.0105
σ	0.0070	0.0140	0.0210
$\sigma\sigma_\epsilon$	0.0070	0.0073	0.0077
$\sigma\Delta$	0.0050	0.0050	0.0050
Volatility, in percent s.d.			
Output	0.9300	1.0100	1.1060
Consumption	0.1450	0.1730	0.2050
Hours	0.1240	0.2850	0.4450
Investment	3.5580	3.8040	4.1060
Capital	0.2430	0.2640	0.2870
$\frac{1}{T} \sum (s^e - s)^2$	0.3900	0.3680	0.2970

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- Confusion falls as regimes become more distinct.

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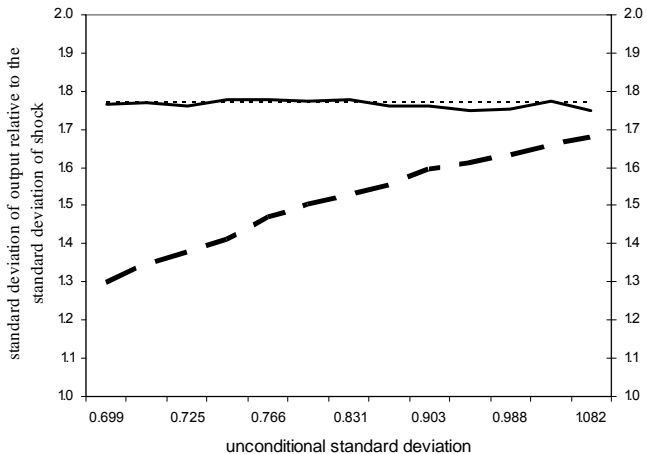
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- We expect to approach complete information as regime distance increases, keeping conditional variance constant.

Figure 2



— Complete Information ····· RBC - - - - Incomplete Information

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 $a_H = a_L = 0.0025$.

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- High volatility: $a_H = a_L = 0.0225$. Low volatility
 $a_H = a_L = 0.0025$.
- This implies $\sigma\sigma_\epsilon = 1.08$ percent in the high volatility case,
and 0.7 percent in the low volatility case.

Moderation accounting

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- The complete information model is close to linear. Output volatility would fall 35 percent in that case. The remaining $50 - 35 = 15$ percentage points is due to learning.

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- The moderation is 30 percent learning and 70 percent good luck.

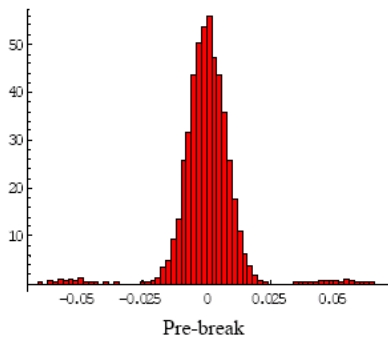
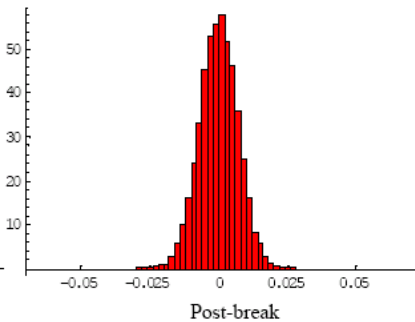
TABLE 3. MODERATION.

Economy

High volatility Low volatility

	Parameter Values	
a_H	0.0265	0.0025
a_L	0.0265	0.0025
σ	0.053	0.005
$\sigma\sigma_\epsilon$	0.0108	0.007
$\sigma\Delta$	0.005	0.005
	Volatility, in percent s.d.	
Output	1.816	0.908
Consumption	0.390	0.138
Hours	1.141	0.082
Investment	6.504	3.487
Capital	0.451	0.238
$\frac{1}{T} \sum (s^e - s)^2$	0.125	0.415

Figure 3

 $ah=al=0.0265$  $ah=al=0.0025$ 

Inference problems

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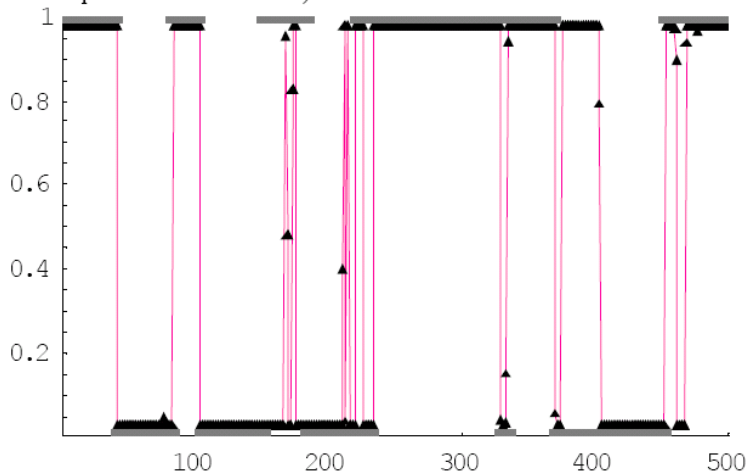
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- There are also self-confirming effects.

Figure 4

Pre-Break $a_h \rightarrow 0.0265$, $a_l \rightarrow 0.0265$ (Sum of Squared Dev= 0.149383 while the average value reported in above is 0.125)



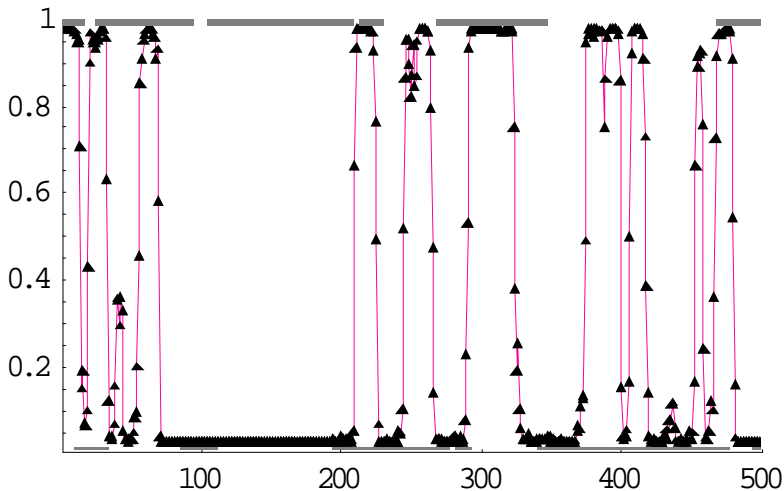


Figure: The true state versus the expected state in the low volatility economy. The agent is relatively confused about the true state, causing moderated behavior.

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- We found this effect might account for 30 percent of a moderation of the magnitude observed in the U.S. in a stylized economy.